Specification

METHOD AND SYSTEM FOR TRANSMITTING ROUTE INFORMATION

<Technical Field>

The present invention relates to a route information

5   transmission method for transmitting a route to a destination

or the like to a receiver side and a system for performing the

method, and more particularly to method and system for

transmitting route information accurately with as small a data

volume as possible.

10 <Background Art>

Conventionally, there have been known vehicular

navigation systems including a GPS receiver and a digital map

in which when a destination is set, a recommended traveling

route from a current point to the destination is calculated and

15 is then displayed. Furthermore, there have been known systems

in which a current point and a destination are transmitted from

an in-vehicle car navigation system to an information center,

a recommended route is calculated by adding traffic conditions

at the information center, and the route so calculated is then

20 provided for the in-vehicle car navigation system.

In addition, on one hand, in most of the conventional

vehicular navigation systems, in order to perform an efficient

and easy-to-understand route guidance while avoiding narrow

roads and complicatedly routed roads, roads for use for route

25 guidance are limited to, for example, roads equal to or wider

than prefectural roads (prefectural roads, national roads, toll

roads and the like) and roads of 5.5m or wider. Due to this, in the event that a final destination is off a road for use for route guidance, while a recommended traveling road to a peripheral point to the final destination is calculated and displayed, there may occur a case where a route from the peripheral point to the final destination is not displayed.

With a view to improving such a drawback, a patent document No. 1 (JP-A-9-178499) discloses a system in which a vehicular navigation system sends information regarding a current point and a final destination to an information center, so that the vehicular navigation system obtains route information from a peripheral point to the final destination to the destination. In this system, the information center estimates, based on the information so received, a peripheral point to the destination which the vehicular navigation system can search, calculates a route reaching from the peripheral point to the final destination to the destination and transmits route information so calculated to the vehicular navigation system. The vehicular navigation system displays the route from the current point to the peripheral point to the destination that it searched and the route from the peripheral point to the final destination to the destination that it received from the information center.

Incidentally, in a case where the information center calculates a recommended route and provides an in-vehicle navigation center with the recommended route so calculated, a

2

route on a map and points along the routes need to be transmitted. However, as inevitable in the case of scale maps, digital map databases contain errors attributed to different map manufacturers. In order to absorb such errors in the digital map databases, in conventional traffic information providing systems such as a VICS system, in order that even in the event that errors exist among the respective maps, a road can be recognized as the same road, node numbers (VICS node numbers) are defined for nodes such as intersections and link numbers (VICS link numbers) are defined for roads between nodes, so that object points for traffic information are represented by the link numbers and node numbers so defined. Information on the node numbers and link numbers is retained in the respective map databases, a vehicular navigation system which complies with VICS can identify an object route or position for traffic information based on the link numbers and node numbers contained in the VICS information, irrespective of the type of the map database installed therein.

When also transmitting a route to a destination, by using these link numbers, the route can be transmitted in the form of route information in which link numbers for links from an starting point to an ending point.

However, node numbers and link numbers defined for the road network need to be renumbered with new numbers, when new roads are built or the existing roads are rerouted, and node numbers and link numbers assigned to the digital map data

3

produced by the respective map manufacturers also need to be renumbered in association with the renumbering. Since building of new roads and rerouting the existing roads continue for ever, as long as the identifying method using node numbers and link numbers continues to be taken, the digital map databases need to be maintained for ever spending lots of man-hours and money, and if any negligence of the maintenance, no accurate road information can be transmitted.

In order to improve these points, a patent document No. 2 (JP-A-2001-66146) proposes a digital map positional information transmitting method in which a transmission side which transmits road segments transmits latitude-longitude information in which latitudes and longitudes at a plurality of points along a road segment are arranged sequentially, and a reception side which has received the information performs a map matching to identify the road segment on its map.

However, in the method for transmitting a route by transmitting latitude-longitude information on a plurality of points along the route, while many points have to be set along the route so that the reception side can reproduce the true shape of the route in order to prevent an erroneous matching on the reception side, when the number of points along the route is increased, the data volume of data to be transmitted is increased, leading to problems that costs for transmitting route information are accumulated and, in addition, that processing loads on the transmission side and the reception side

4

are increased.

<Disclosure of the Invention>

The invention was made to solve the conventional problems and an object thereof is to provide a route information transmission method for transmitting a recommended route or a guided route to a reception side accurately and with as small a data volume as possible and a system for performing the method.

Then, according to the invention, there is provided a route information transmitting method which is characterized in that a transmitting side provides a receiving side which requests route information with compressed data obtained by arithmetically processing positional data of a plurality of points aligned along a route so as to convert the positional data into statistically biased data and variable length coding the statistically biased data so converted, and in that the receiving side identifies the route by decoding the compressed data so as to restore the positional data.

Due to this, the route information can be transmitted accurately with a small volume of data.

In addition, according to the invention, there is provided a route information providing apparatus which is characterized by comprising a transmitting means for transmitting a request for the provision of route information, a receiving means for receiving compressed data provided and a means for decoding the compressed data so as to restore positional data of a plurality of point aligned along a route.

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Due to this, the route information receiving apparatus can identify the route accurately from the information of a small volume of data.

<Brief Description of the Drawings>

5   Fig. 1 is a block diagram illustrating the configuration of a recommended route providing system according to a first embodiment of the invention;

Fig. 2 is an exemplary drawing illustrating the recommended route providing system according to the first

10   embodiment of the invention;

Fig. 3 is a data configuration drawing of recommended route information transmitted by the recommended route providing system according to the first embodiment of the invention;

15   Fig. 4 shows drawings explaining a variable length coding by a route information transmission method according to the first embodiment of the invention;

Fig. 5 is a drawing showing a code table used in the route information transmission method according to the first

20   embodiment of the invention;

Fig. 6 is a block diagram illustrating the configuration of a running route providing system according to a second embodiment;

Fig. 7 is an exemplary drawing illustrating the running

25   route providing system according to the second embodiment of the invention; and

Fig. 8 is a data constitution drawing illustrating running route information transmitted by the running route providing system according to the second embodiment of the invention.

In addition, reference numerals in the drawings denote respectively as below:

10: running route storing and transmitting device; 11: information request range information receiving unit; 12: running route information extracting unit; 13: running route information storage unit; 14: running route manual inputting unit; 15: running route compression encoding unit; 16: running route information transmitting unit; 20: running route information utilizing device; 21: information request range transmitting unit; 22: information request range calculating unit; 23: running route information receiving unit; 24: compressed data decoding unit; 25: digital map database; 26: map matching unit; 27: running route information utilizing unit; 30: route calculating device; 31: start point and destination information receiving unit; 32: route calculating unit; 33: traffic information collecting unit; 34: route information compression encoding unit; 35: route information transmitting unit; 40: route information utilizing device; 41: start point and destination information receiving unit; 42: subject vehicle position calculating unit; 43: destination information inputting unit; 44: route information receiving unit; 45: compressed data decoding unit; 46: map matching unit;

7

47: digital map database; 48: route information utilizing unit; 51: probe car; 52: probe car; 53: sensor; and 54 sensor.

<Best Mode for Carrying out the Invention>

Embodiments of the invention will be described below by

5   reference to the drawings.

(First Embodiment)

In a first embodiment of the invention, a case will be described in which information on a recommended route to a destination is transmitted.

10   In a route information transmitting method according to the first embodiment of the invention, sampling points are reset at intervals of a constant distance along a recommended route (this being referred to as *equidistant re-sampling*), a compression encoding treatment is applied to a data string in

15   which position data of the respective sampling points are aligned sequentially and compression encoded data are transmitted. A receiving side which receives them restores the data string of the position data of the sampling points to thereby identify the recommended route.

20   Furthermore, in order to identify the route information so received more accurately, an object road is identified on its own digital map data by performing a matching with its own digital map data. In addition, when also performing a route guidance (voice guidance and enlarged display of intersections

25   and interchanges, deformed display), as has been described, an object road needs to be identified on a digital map database

8

held in its own device by performing a matching.

In the event that there exists no road corresponding to the received route information on its own digital map database, assuming that the object road is a newly opened road, a route guidance is performed.

The compression encoding of the data string of position data is performed in the following order; ① Conversion of the position data into a single variable, ② Conversion of a value represented by the single variable into a statistically biased value, and ③ Variable length coding of the converted value.

(1) Conversion of Position Data into Single Variable

Fig. 4A shows sampling points set along the recommended route in the equidistant re-sampling as PJ-1, PJ. The sampling point (PJ) can uniquely be identified in two dimensions of a distance L from the adjacent sampling point (PJ-1) and an angular component Θ, and assuming that the distance is constant (L), the sampling point (PJ) can be represented by one variable of only the angular component Θ from the adjacent sampling point (PJ-1). In Fig. 4A, as this angle Θ, an angle Θ is shown which is represented by an *absolute orientation* which designates the magnitude in a range of 0 to 360 degrees measured clockwise from the orientation of true north (top on the map) which is regarded as 0 degree. Assuming that the x-y coordinates (latitude, longitude) of PJ-1 and PJ are (x_{j-1}, y_{j-1}) and (x_j, y_j), respectively, this angle Θ_{j-1} can be calculated from the following equation:

$$\Theta_{j-1} = \tan^{-1}\{(x_j - x_{j-1})/(y_j - y_{j-1})\}$$

Consequently, the recommended route can be represented by a data string of angular components of the respective sampling points by designating the constant distance L between the sampling points and latitude and longitude of the sampling point (reference point) which constitutes a starting point or an ending point separately.

(2)   Conversion of Single Variable Value into Statistically Biased Value

In order for a single variable value of each sampling point to become a statistically biased value which is suitable for variable length coding, as shown in Fig. 4B, the angular component of each sampling point is represented by a displacement difference from the angular component of the adjacent sampling point, that is, a deviation *angle* Θ_j. This deviation angle Θ_j is calculated as:

$$\Theta_j = \Theta_j - \Theta_{j-1}$$

In the event that the road is rectilinear, the deviation angle of each sampling point focuses on the vicinity of 0 and becomes statistically biased data.

In addition, as shown in Fig. 4C, the angular component of the sampling point can be converted into statistically biased data by representing the deviation angle θ_j of the sampling point PJ, to which attention is to be paid, by a difference value (deviation-angle estimated difference value) $\Delta\theta_j$ from a deviation angle estimated value S_j (statistically estimated

10

value) of the sampling point PJ which is estimated using deviation angles θ_{j-1}, θ_{j-2}, . . . of the previous sampling points PJ-1, PJ-2, ... The statistically estimated value S_j can be defined as, for example:

$$S_j = \theta_{j-1}; \text{ or}$$

$$S_j = (\theta_{j-1} + \theta_{j-2}) / 2$$

In addition, S_j may be defined in terms of a weighted average of deviation angles at the n previous sampling points. The deviation-angle estimated difference value $\Delta\theta_j$ is calculated as:

$$\Delta\theta_j = \theta_j - S_j$$

In the event that the road curves at a constant curvature, a deviation-angle estimated difference value $\Delta\theta$ of each sampling point focuses on the vicinity of 0 and becomes statistically biased data.

Fig. 4D is a graph illustrating frequency at which data are generated when the rectilinear recommended route is represented by the deviation angle θ and when the curved recommended route is represented by the deviation-angle estimated difference value $\Delta\theta$. The generation frequency of θ and $\Delta\theta$ becomes maximum when $\theta = 0°$ and is statistically biased.

(3)   Variable Length Coding

Next, the value of the data string which is converted into the statistically biased value is variable length coded. While the variable length coding method includes many types of methods such as fixed numerical value compression method (0 compression

11

or the like), Shannon-Fanno coding method, Huffman coding method, arithmetic coding method and lexicographic coding method, here a case will be described in which Huffman coding method, which is the commonest, is used.

5   In this variable length coding, more frequently generated data are coded by bits in a smaller number and less frequently generated data are coded by bits in a greater number, so that the total data volume is reduced. A relationship between the data and codes are defined in a code table.

10   Now, assume that the arrangement of Δθs at sampling points along the recommended route which are represented in a unit of 1° is as follows:

          "0_0_-2_0_0_+1_0_0_-1_0_+5_0_0_0_+1_0"

A case will be described where a code table shown in Fig. 5 in
15 which variable length coding and run length coding are combined is used in order to code the data string. The code table regulates such that Δθ which is in the range of -1° to +1° is regarded as 0° and is then represented by a code 0, in a case where 0° occurs continuously five times, it is represented by
20 a code 100, and in a case where 0° occurs continuously ten times, it is represented by a code 1101. In addition, Δθ which is in the range of +/-2° to 4° is regarded as +/-3° and when it is positive, Δθ is then represented by adding an additional bit 0 to a code 1110, whereas when it is negative, Δθ is then
25 represented by adding an additional bit 1 to the code 1110, Δθ which is in the range of +/-5° to 7° is regarded as +/-6° and

12

is then represented by adding an additional bit denoting positive or negative to a code *111100*, and Δθ which is in the range of +/-8° to 10° is regarded as +/-9° and is then represented by adding an additional bit denoting positive or negative to
5 a code *111101*.

Due to this, the data string is coded as follows:

"0_0_11101_100_0_0_1111000_100"

→ "00111011000001111000100"

The receiving side which has received the data restores
10 the data string of Δθs using the same code table as that used in coding and reproduces the position data of the sampling points by performing an opposite process to that implemented on a transmitting side.

Fig. 2 exemplarily illustrates a system for providing
15 recommended route information using this route information transmitting method, and additionally, Fig. 1 illustrates the configuration of the system in a block diagram.

A route calculating device 30 for providing route information includes a start point and destination information
20 receiving unit 31 for receiving information on start point and a destination from a route information utilizing device 40 such as a vehicular navigation system, a traffic information collecting unit 33 for collecting information from ultrasonic vehicle sensors and image sensors which are placed along each
25 road or various types of sensors 53, 54 such as probe cars functioning as running traffic information collecting sensors

13

and also collecting information on an unexpected event such as an accident which is entered manually, a route calculating unit 32 for calculating a recommended route from the start point to the destination and a required time (a traveling time) to cover

5   the route while referring to the traffic information collected by the traffic information collecting unit 33, a route information compression encoding unit 34 for compression encoding the information on the recommended route, and a route information transmitting unit 35 for transmitting data of the

10   compression encoded recommended route and traveling time information to the route information utilizing device 40.

Then, the route information utilizing device 40 includes a subject vehicle position calculating unit 42 for detecting the position of the subject vehicle using a GPS function or the

15   like, a destination information inputting unit 43 for inputting a destination, a start and destinations information transmitting unit 41 for transmitting information on the current point and the destination to the route calculating device 30, a route information receiving unit 44 for receiving

20   recommended route information from the route calculating device 30, a compressed data decoding unit 45 for decoding the compression encoded data, a digital map database 47, a map matching unit 46 for performing a map matching of the position data of the decoded recommended route with digital map data to

25   thereby identify the recommended route on a digital map and a route information utilizing unit 48 for displaying the

14

recommended route.

In this system, when the user enters a traveling destination from the destination information inputting unit 43 of the route information utilizing device 40, requesting the provision of route information to the destination, the route information utilizing device 40 transmits the current point detected by the subject vehicle position calculating unit 42 and the destination inputted from the destination information inputting unit 43 to the route calculating device 30.

Then, in the route calculating device 30, vehicle detection information taken by the ultrasonic vehicle sensors and image sensors which are placed along each road is collected to the traffic information collecting unit, and, in addition, information on the speed measured by the running probe car is sent to the traffic information collecting unit 33 via cellular phones and beacons. In addition, information on traffic accidents or road constructions which are entered manually is also collected to the traffic information collecting unit 33.

When receiving the information on the current point and the destination which was sent from the route information utilizing device 40, the route calculating unit 32 of the route calculating device 30 refers to the traffic information collected by the traffic information collecting unit 33 and then calculates several recommended routes and traveling times which allow the user to reach from the current point to the destination in a short period of time. The route information compress

encoding unit 34 performs an equidistant re-sampling as to the recommended route calculated by the route calculating unit 32 so as to variable length code a data string of the position data of the sampling points using the aforesaid method. Information on the compression encoded data string regarding the recommended route and the traveling time is sent from the route information transmitting unit 35 to the route information utilizing device 40.

Fig. 3 illustrates the data configuration of the recommended route information sent from the route calculating device 30. Here, in coding, either deviation angles or deviation-angle estimated difference values are used as *coding parameters*, or, information on the constant distance L set in the equidistance re-sampling, identification numbers in the code table and latitude and longitude of the reference point (start point, destination) is described, the number of recommended routes that are provided is described as the *number of routes provided*, and furthermore, the route shape is described which is represented by the traveling time of each recommended route and the data string of variable length coded data.

In the route information utilizing device 40, which has received the recommended route information, the compressed data decoding unit 45 decodes the data string of coded route shape data and restores the position data of the sampling points aligned along the recommended route. As this occurs, the

16

compressed data decoding unit 45 performs the decoding of the route shape data using a code table of an identification number designated by the coding parameters among a plurality of code tables given in advance from the route calculating device 30

5   and held.

The map matching unit 46 obtains points along the road which correspond to the sampling points on the recommended route in a known map matching method using map data of the digital map database 47 and identifies the recommended route on the

10   digital map.

The route information utilizing unit 48 displays the recommended route on a screen and guides a traveling direction of the vehicle along the recommended route via voice or enlarged views of intersections and interchanges.

15   Thus, in this system, since the shape data of the recommended route are coded and transmitted, the volume of data transmitted becomes small.   In addition, the receiving side can identify the recommended route accurately through map matching.

In the route information transmitting method described

20   in the patent document No. 1, while the information sent to the vehicular navigation system from the information center (the route calculating device) with the route from the current point to the final destination being calculated thereby is limited only to the route information from the peripheral point to the

25   final destination to the destination, in the route information sending method according to the first embodiment of the

17

invention, since the volume of data that are transmitted is small, the route information from the current point to the final destination can be transmitted without causing the transmitting side and the receiving side to bear a great load.

Note that while in this embodiment, the case has been described in which the recommended route is re-sampled equidistantly, and the angular components of the position data at the sampling points are converted into the statistically biased value for the variable length coding, it is possible to perform the variable length coding by setting a sampling point along the recommended route in such a manner that the deviation angle becomes constant and converting the distance L_j to the adjacent sampling point into a statistically biased value (for example, a distance estimated difference value ΔL_j is obtained from $\Delta L_j = L_j - S_j$ by defining $S_j = L_j - 1$). In addition, it may be possible to perform the variable length coding by setting nodes and interpolating points (points set on the map to represent the shape of the route) along the recommended route as sampling points and converting both angular component θ_j and distance component L_j, which are made to function as variables, into statistically biased values.

(Second Embodiment)

In a second embodiment of the invention, a system for providing information indicating the traveling path of other vehicles will be described.

For example, a running storing and transmitting device

18

10 includes an information request range information receiving unit 11 for receiving information designating an area from a running route information utilizing device 20 such as a vehicular navigation system and a personal computer, a running route manual inputting unit 14 for manually inputting a running route, a running route information storing unit 13 for storing running routes sent from respective probe cars 51, 52 or running routes inputted from the running route inputting unit 14, a running route information extracting unit 12 for extracting a running route within an information request range (area or date and time band) designated by the running route information utilizing device 20 among the running routes stored in the running route information storing unit 13, a running route compression encoding unit 15 for compression encoding the running route so extracted and a running route information transmitting unit 16 for transmitting the compression encoded running route to the running route information utilizing device 20.

In addition, the running route information utilizing device 20 includes an information request range calculating unit 22 for setting an information request range, an information request range transmitting unit 21 for transmitting the information request range so set to the running route storing and transmitting device 10, a running route information receiving unit 23 for receiving running route information from the running route storing and transmitting device 10, a

compressed data decoding unit 24 for decoding data of a compression encoded running route, a database of digital maps, a map matching unit 26 for performing a map matching of position data of the running route so decoded with the digital map data

5   to thereby identify the running route on the digital map, and a running route information utilizing unit 27 for displaying the running route.

In this system, the running route information utilizing device 20 such as a vehicular navigation system and a personal

10 computer determines an information request range, that is, the type of a day (week days, holidays and the like) and a time band (the peak hours of traffic on the morning roads, the peak hours of traffic on the evening roads, slack hours on night roads) and transmits the information request range so determined to

15 the running route storing and transmitting device 10.

Then, in the running route storing and transmitting device 10, traveling path of the probe cars 51, 52 are transmitted thereto via cellular phones and beacons or stored on a storage medium such as a flexible disk for input thereinto,

20 whereby the traveling path so transmitted or inputted are stored in the running route information storing unit 13. In addition, a running route inputted from the running route manual inputting unit 14 is also stored in the running route information storing unit 13.

25 The running route extracting unit 12 extracts a running route falling within the information request range from running

routes stored in the running route information storing unit 13.
As in the case with the first embodiment, the running route
compression encoding unit 15 performs an equidistance
re-sampling on the running route so extracted so as to variable

5   length code a data string of position data of the sampling point
by the aforesaid method. The running route information so
compressed is transmitted from the running route information
transmitting unit 16 to the running route information utilizing
device 20 which requested the provision of the information.

10   Fig. 8 illustrates the constitution of data of route
information sent from the route calculating device 30. Here,
together with *encoding parameters* and *the number of locus data
to be provided*, the profile (the time of the day of the month
in the year when the running was carried out, traveling time

15   and the like) of each traveling path and the shape of the running
route represented by the data string of variable length encoded
data are described.

In the running route information utilizing device 20, the
compressed data decoding unit 24 decodes the encoded data string

20   of running route shapes so as to restore the position data of
the sampling points aligned along the running route. As this
occurs, the compressed data decoding unit 24 decodes the data
of the shape of the running route using a code table of
identification numbers which is designated by the coding

25   parameters from a plurality of code tables given in advance by
the running route storing and transmitting device 10 and held

therein.

The map matching unit 26 obtains positions along the road which correspond to the sampling points along the running route by a known map matching method, using the map data of the digital
5 map database so as to identify the running route on the digital map.

The running route information utilizing unit 27 displays the running route on the screen.

Thus, in this system, by compression encoding the
10 information of traveling path requested by the receiving side, the running route information can be transmitted in a small volume of transmission data. In particular, in a case where a taxi driven by a professional driver or a vehicle driven by a person who lives in the vicinity of a target place is designated
15 as a probe car, so that traveling path of the taxi of vehicle are stored, running route information can be provided which is far more valuable as route information than running route information that would be obtained through driving of a vehicle by a driver who is not familiar with the target place.

20 Thus, while the invention has been described in detail or by reference to the specific embodiments, it is clear to those skilled in the art that various changes and/or modifications can be made thereto without departing from the sprit and scope of the invention.

25 The patent application of this invention is such as to be based on the Japanese Patent Application (No. 20030125340)

and the contents thereof are incorporated herein by reference.

<Industrial Applicability>

As is clear from the description that has been made heretofore, the route information transmitting method according to the invention can transmit the route information accurately in a small volume of data.

In addition, the device according to the invention can transmit or receive information effective in supporting the driving of a vehicle such as a route to a destination and traveling path of the past driving by the route information transmitting method.